COMS30026 Design Verification Stimuli Generation (Part I)

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Outline

Motivation: Advanced Stimuli Generation

Running example: PowerPC processor

Part I: Issues in stimuli generation

- How many generators?
- Level of abstraction
- Online vs. offline generation
- Dynamic vs. static generation
- Test length

Part II: Test Automation

- Randomness
- Constrained pseudo-random stimulus generation

- Achieve all the items in the test scenarios matrix of the verification plan
- Ensure that the scenarios in the matrix are happening
 - Ensure that any anomalies are propagating to an existing checker
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 - Ensure that nothing gets broken over time

Running Example – PowerPC Processor

- Black box view
 - Interface to memory (via caches)
 - For instruction fetching
 - For data fetching and storing
 - Interface to I/O devices
 - For data fetching and storing
 - Interrupts
 - Miscellaneous interface
 - Clocks
 - Reset



Architectural View

- RISC (Reduced Instruction Set Computer) processor
 - "Small" number of instructions (~400)
 - One simple operation per instruction
 - Fixed length instructions (32 bits = 1 word)
 - Specific load and store instructions to access memory
 - All other instructions use registers for operands
- Large register files
 - 32 general purpose registers (GPR)
 - 32 floating-point registers (FPR)
 - Used only for floating-point operations
 - Several special purpose registers
 - Condition register, link register, status register, etc.
- Complex memory model
 - Multiple level address translation
 - Coherency rules
 - (not in the scope of the lecture)

Microarchitectural View



Extracts from the Verification Plan

- 1. Check that all pairs of instructions are executed correctly together
 - Basic architectural requirement
 - Appears in most verification plans of processors
 Fulfilling it is not as easy at it seems
- 2. Check that all forwarding mechanisms between pipeline stages are working properly
 - Basic microarchitectural requirement
 - Source for many bugs in previous designs



Processor Verification Environment



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Issues in Stimuli Generation

- How many generators?
- Level of abstraction
- Online vs. offline generation
- Dynamic vs. static generation
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How Many Generators?

- Distributed generators
 - Each interface has its own generator
 - Each generator works on its own
 - Advantages
 - Simple
 - Easy to reuse
 - Disadvantages
 - Hard to reach corner cases in coordinated fashion



How Many Generators?

- Single generator
 - One generator controls all the interfaces
 - Advantages
 - All the interfaces can work together toward a common goal
 - Disadvantages
 - Complex
 - Hard to reuse



How Many Generators?

- Synchronized generators
 - Each interface has its own generator
 - The generators share information and synchronize
 - Advantages
 - Can reuse each generator separately
 - Can work together towards a common goal



Abstraction Level of Generation





Abstraction Level of Generation



While bit-level representation allows us to see how the data exercises the carry chain, at a higher level of abstraction (looking at the integer values) we may not spot this.

What Does Abstraction Level Mean?

- Communication between the user and the generator
 How the user specifies directives to the generator
- Internal representation and operation level in the generator
 The level in which the generator generates the stimuli
- Communication between the generator and the driver
 - The generator sends information at high level of abstraction
 - The driver translates into bits using the appropriate protocol



Which Abstraction Level To Choose?

- Communication between the user (verification engineer) and the generator
 - Use a level similar to the level used in the verification plan
 - In our case (running example) the sequence level



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- Conflicting requirements
 - Address user requirements (at their level) \rightarrow high level of abstraction
- ✓ Need sufficient detail → low level of abstraction
 - In many cases we use two or more levels for stimuli generation
 - First we build a high-level skeleton of the stimuli based on the user requirements
 - Next we add lower-level details



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- In many cases we use two or more levels for stimuli generation
 - First we build a high-level skeleton of the stimuli based on the user requirements
 - Next we add lower-level details
- Communication between the test generator and the driver
 - Use the lowest level in which the test generator operates
 - Special case error injection

Error Injection

- Error detection and recovery are very important mechanisms in hardware designs
 - They are also very hard to verify
- Error injection is usually done at the lowest level of abstraction
 - The value of a bit (or set of bits) is flipped when they are injected into the DUV
- To allow error injection, the generator needs to operate and communicate with the driver at the bit level
 - This creates extra burden and unnecessarily increases complexity for normal cases



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- Possible solution create a separate error injection interface between the test generator and driver

At the low level of the error injection, i.e. directly injecting the error
 At the normal level with instructions on how to inject the error

Online vs Offline Generation

When to generate stimuli?

- Offline generation (pre-run):
 - The entire stimuli are generated before the simulation begins
 - The generation and simulation can be two separated processes

Online generation (on-the-fly):

- Stimuli generation during simulation
- The next element is generated when needed by the driver
- The generator must be part of the verification environment



Offline Generation

- Why
 - Can separate the test generation from simulation
 - Use external tools, emulation, …
 - Can use more complex algorithms for test generation
 - For example, generate "out of order", e.g. instruction sequences (processors) or action sequences (robotics)
 - Offline test generation may be compulsory
- Why not

Where?

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 - Offline test generation may be compulsory Where?
- Why not
 - Need to connect the test generation output to the verification environment
 - Cannot use information directly from the DUV during simulation, nor from the environment
 - Hard to react to unexpected but valid responses from the DUV

Generating Instructions Out Of Order

- Verification goal: forward data from M2 to B2
 Branch is dispatched after arithmetic instruction
 - Both reach stage 2 together
 - To preserve functional correctness, the branch must wait for the arithmetic instruction to complete





Decode

How can we generate a test, i.e. a sequence of instructions, that achieves this goal (efficiently and effectively)?

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Decode

Generation Order: <u>Br</u> – <u>Mul</u> – <u>Div – Lw – Add</u> Execution Order: Lw – Add – <u>Mul</u> – Div – <u>Br</u>

Online Generation

- Why
 - The generator can use information about the state of the environment and DUV for improving the quality of generation
 - Makes reaching corner cases easier
 - The only solution to react to unexpected but valid behaviour of the DUV
 - Generally small memory footprint
- Why not



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 - Must generate items in order
 - Limited complexity
 - <any other reasons why not>



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- Why not
 - Must generate items in order
 - Limited complexity
- Performance: online test generation slows down simulation



Mixing online and offline Generation

- Online and offline generation can be mixed within a verification environment
- Which designs would benefit from this combination?



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Processor verification: instruction sequences are generated from high-level programs through compilation, i.e. offline using an external tool – the compiler, but the interrupts are generated online, when the processor is in an interesting state. ③



Dynamic vs. Static Generation

- In static generation the test generator is not aware of the state of the DUV and the environment
 - Generation decisions are based entirely on the internal state of the test generator
- Alternatively, we can take a less restrictive view on static generation: the test generator is aware of what and when it is allowed to generate
 - In calc1 the generator knows not to generate a new command before a response for the previous command has been received
- In dynamic generation the test generator is fully aware of the state of the DUV and the environment and generates based on this information
 - The test generator can react to interesting states in the DUV

Dynamic Instruction Generation Example

- Verification goal: forward data from M2 to B2
 - The generator identifies the potential forwarding condition "on the fly", i.e. when it spots the mul instruction
 - It generates instruction(s) that will block the br(anch) from dispatching with the mul instruction
 - It generates a br instruction Data Fetch that uses the same register as the destination of the mul instruction to create the Write Bac dependency that triggers forwarding



Does This Example Work?

- This example may not work!
- Main reason:
 - There is a distance (in terms of time) from the entry point of instructions into the processor to the dispatch queue. This distance creates delays.
 - Many bad things can happen while the br instruction travels this distance

For example, exceptions that flush the pipes

 By the time the br instruction reaches the relevant stage in the pipe to trigger forwarding,
 the interesting condition may already have gone

Dynamic vs. Static Generation

- Dynamic test generation is based on reaction while static test generation is based on planning
- In general, reaction is harder than planning
 - Time is a factor
 - Unexpected events can get in the way
- Most generators use dynamic features lightly
 - Observe and react to shallow or stable states of the DUV
 - For example, architectural registers or the state of a fifo, e.g. it being almost full.



Offline Dynamic Generation

- Dynamic and static generation should not be confused with online and offline generation
- An offline generator can use dynamic generation by using a reference model that provides information about the state of the DUV
 - The level and accuracy of the information depends on the abstraction level and accuracy of the reference model

Test Length

- Two extreme approaches for selecting the test length
- Use short tests
 - The shortest tests that can fulfill the requirement in the verification plan
 - For the instruction pairs requirement use tests with just two instructions ⁽²⁾
- Use long tests
 - Combine many requirements in a single test
 - Wrap a test with initial and end sequences



Why Short Tests?

- Easy to create
- Easy to debug
- Easy to maintain
- Short time to simulate each



Short tests vs. long tests



Why Long Tests?

- Need fewer tests
- Less time to simulate
 - Overall less time as we do not need to repeat the initialization sequence for every test ;)



Why Long Tests?

- Need fewer tests
- Less time to simulate
 - Overall less time as we do not need to repeat the initialization sequence for every test ;)
- Test is not at or near the initial state most of the time, which is the case when using short tests
- Go along less traveled paths, which results in a greater variety in terms of exercising the logic
- Reach verification targets in different ways
 - Often leads to reaching the targets in unexpected ways

Summary of Part I

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